

tinyML[®] EMEA

Enabling Ultra-low Power Machine Learning at the Edge

tinyML EMEA Technical Forum 2021 Proceedings

June 7 – 10, 2021

Virtual Event



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tinyML EMEA Technical Forum 2021

June 7-10, 2021

TOD: Transprecise Object Detection to Maximise Real-Time Accuracy on the Edge

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Acknowledgement

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DiPET Website : <https://dipet.eecs.qub.ac.uk>

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- Edge for Real-Time Video Analytics (RTVA)

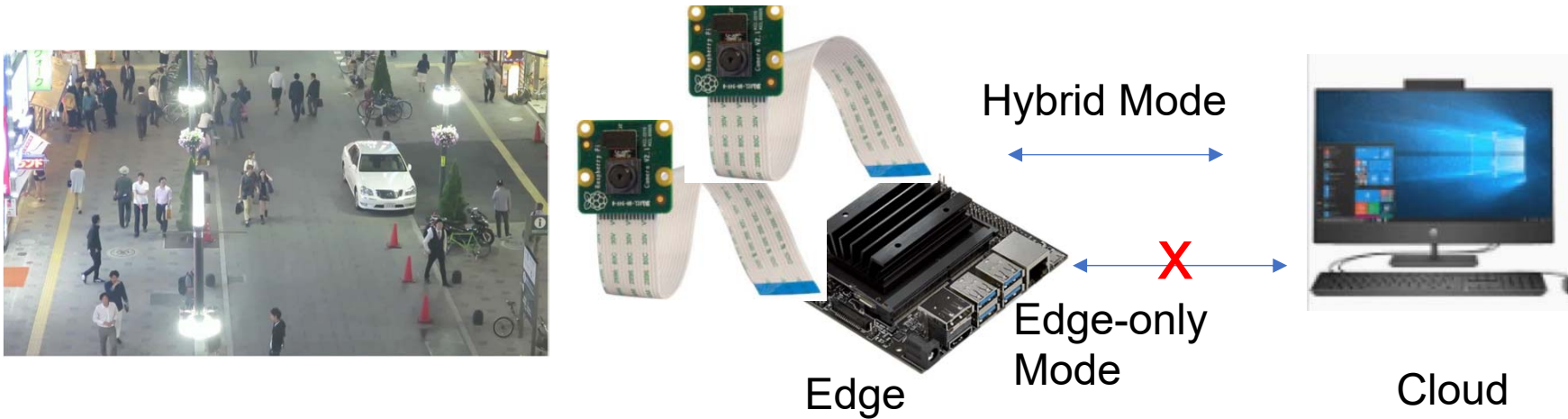


Figure Source: Multi Object Tracking 17 Dataset (<https://motchallenge.net>)

- Challenges in RTVA on the Edge: Limited Computational Power → Longer Inference Latency from Deep Neural Network (DNN) → More Dropped Frames → *Limited Object Detection Accuracy*



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TOD: Transprecise Object Detection (to maximise RTVA accuracy on the Edge)

- Initialization: Preloading 4 different YOLOv4 detectors into GPU RAM
- Runtime Scheduler (RS) Selects a DNN on the Fly according to Dynamic Object Sizes Detected.
- TOD Demonstration when objects are fading away from camera (i.e., objects are getting smaller.)

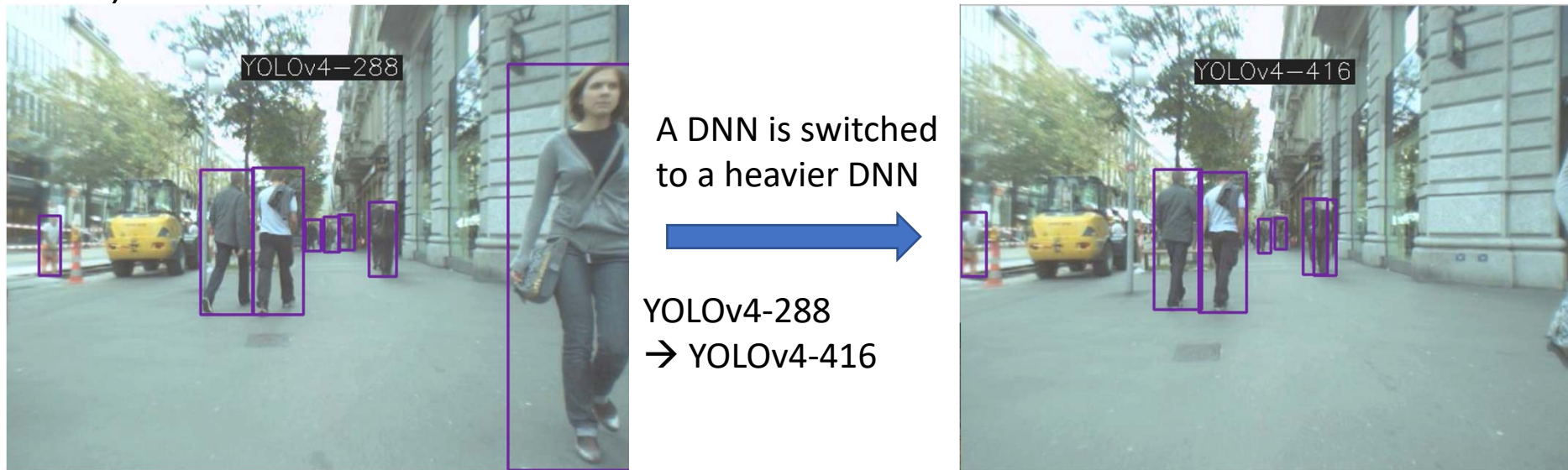


Figure Source: Multi Object Tracking 17 Dataset (<https://motchallenge.net>)

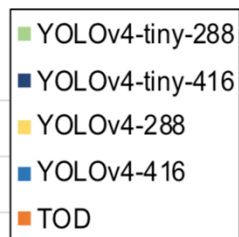


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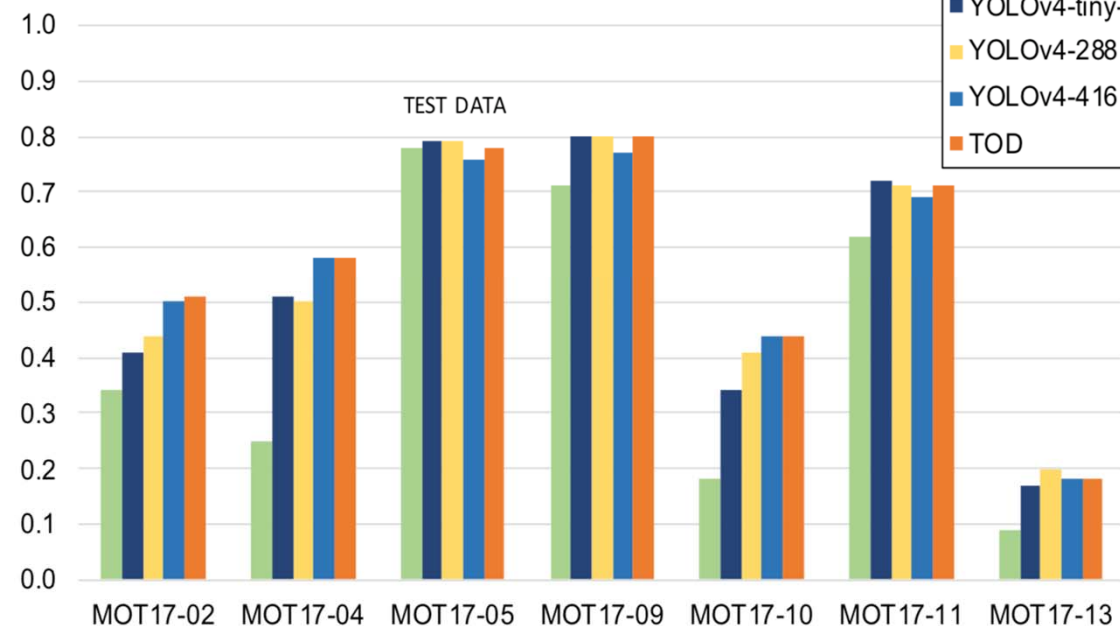
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Experimental Evaluation with a NVidia Jetson Nano Board with MAX power mode

Average Precision (Real-Time) including TOD



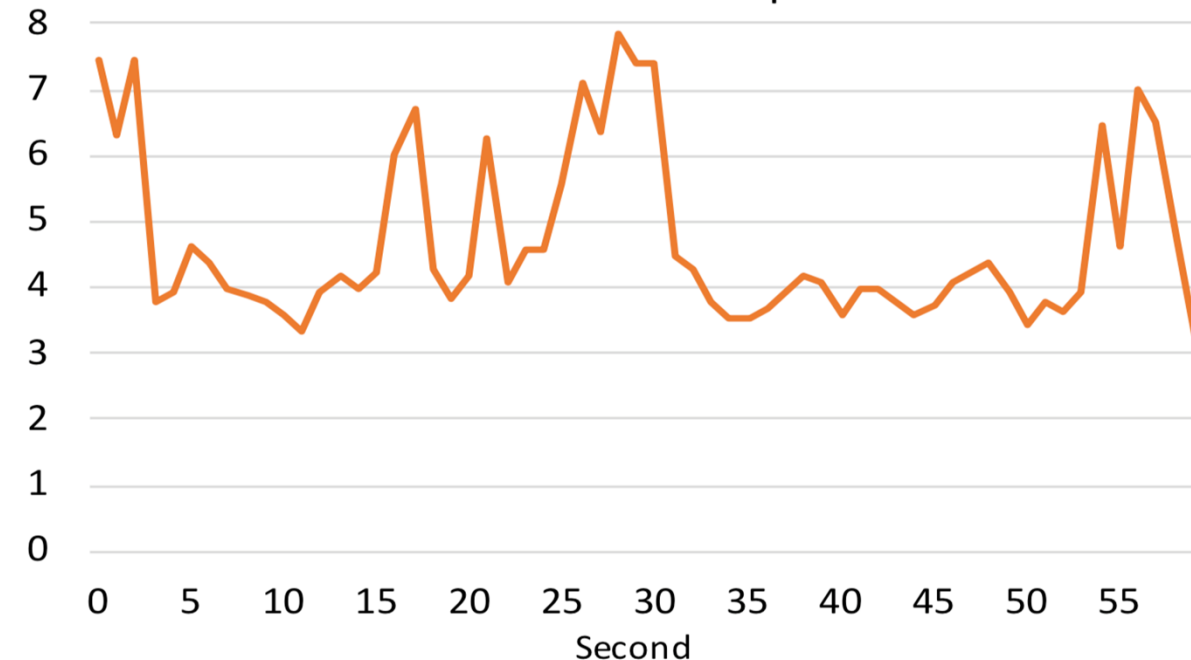
TEST DATA



Best (or equivalently good) accuracy for all cases
- 35% gain over YOLOv4-tiny-288.

Watt

TOD Power Consumption



With MOT17-05 data, TOD requires 63% of the power without losing accuracy compared to YOLOv4-416. (TOD: 5.7W, YOLOv4-416: 7.5W)

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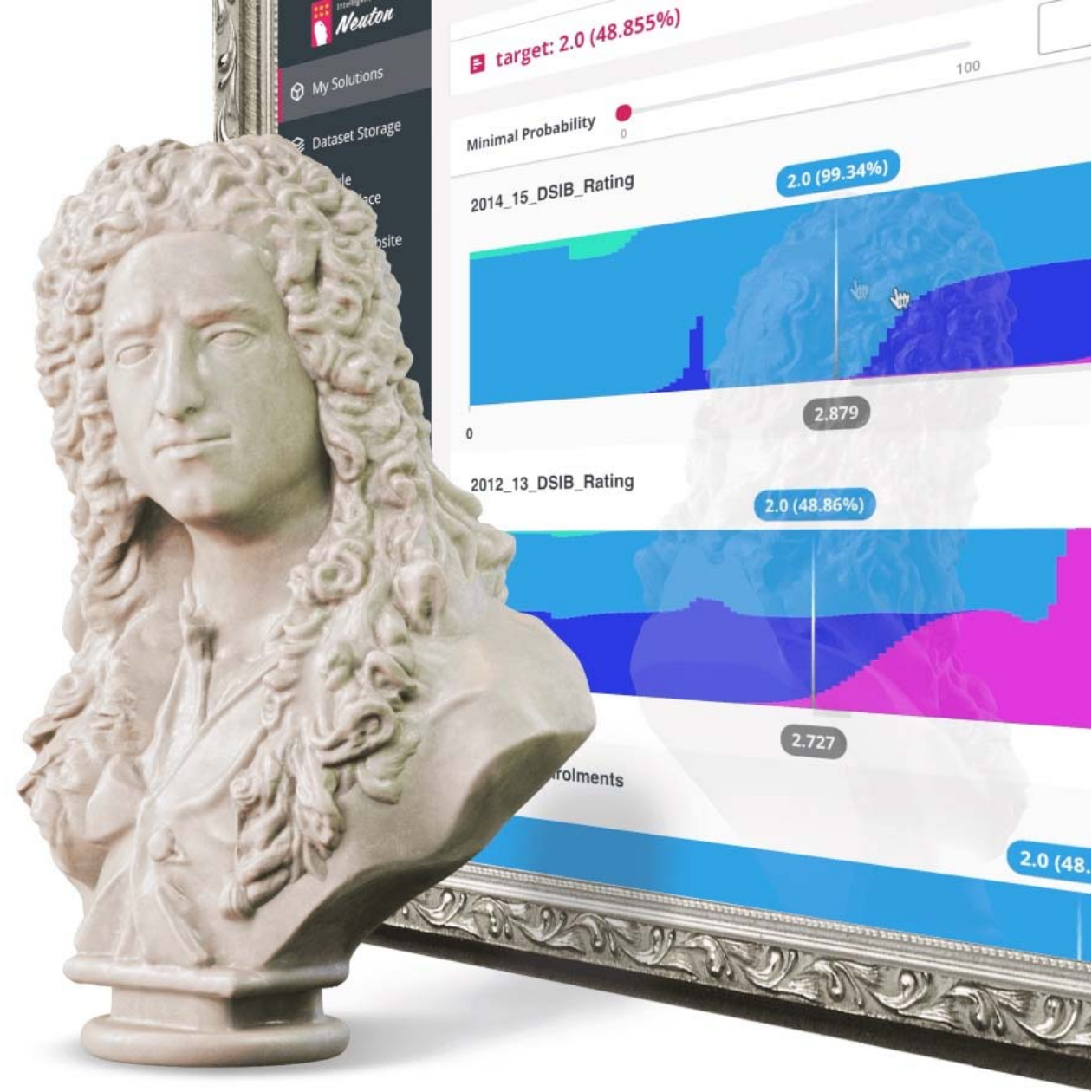
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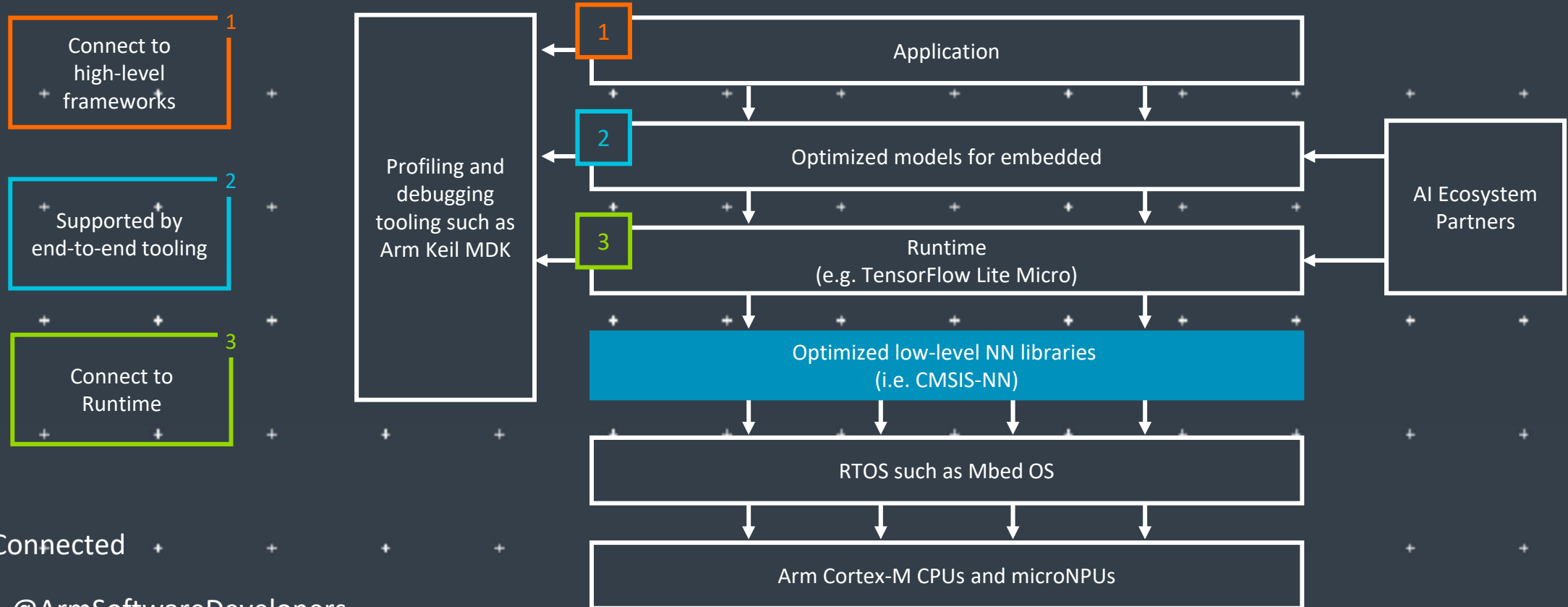
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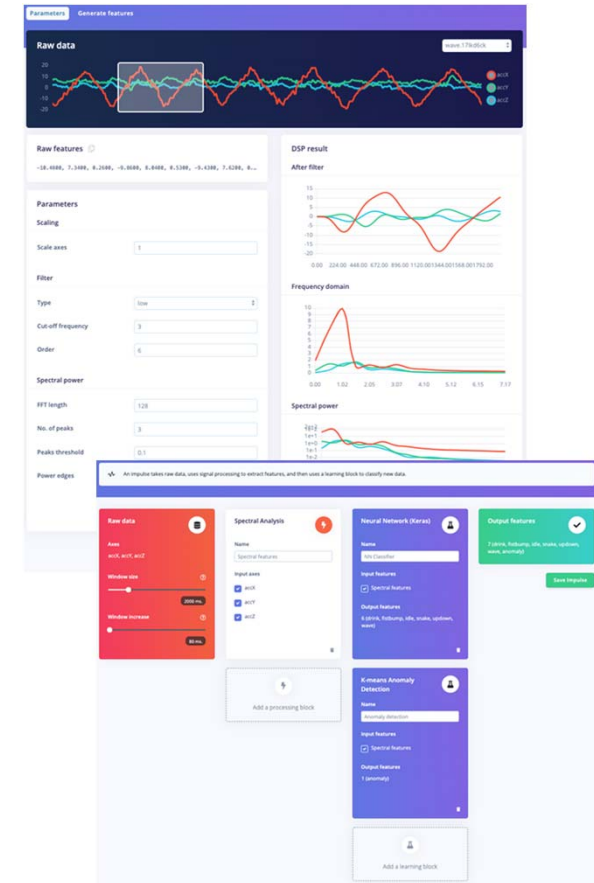
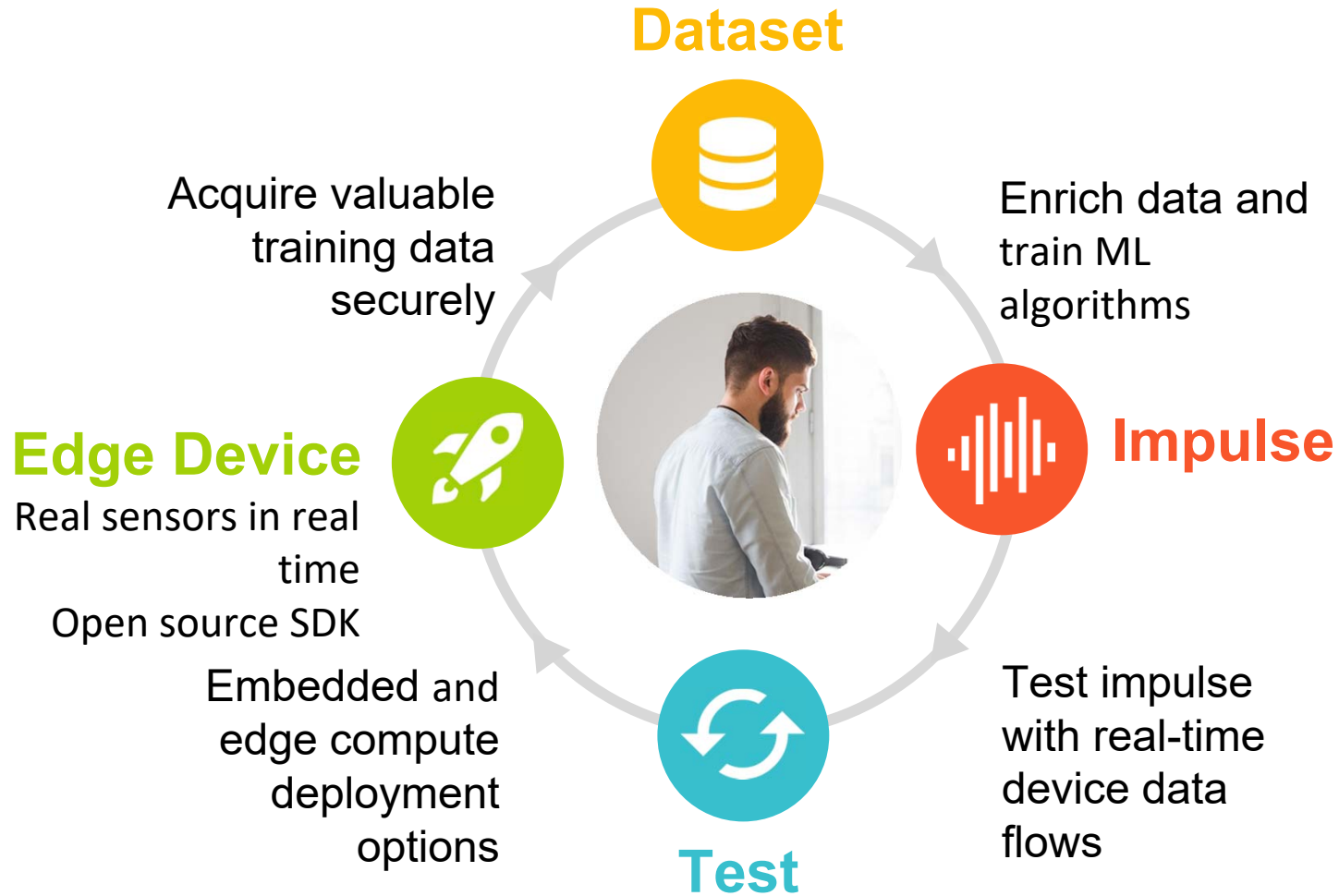
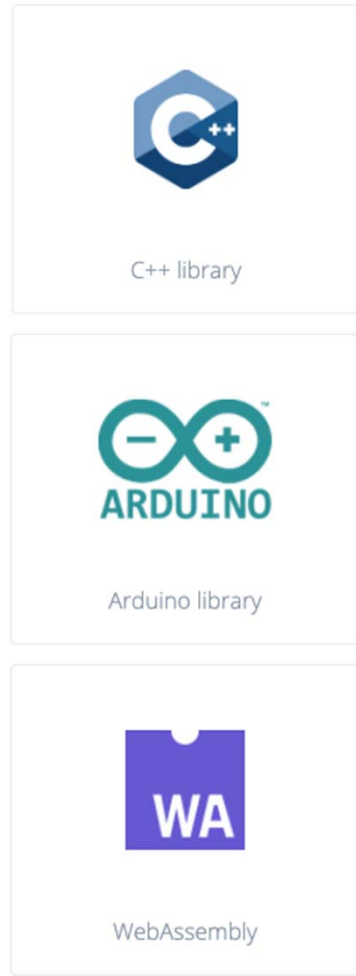
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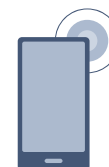
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IoT/IIoT



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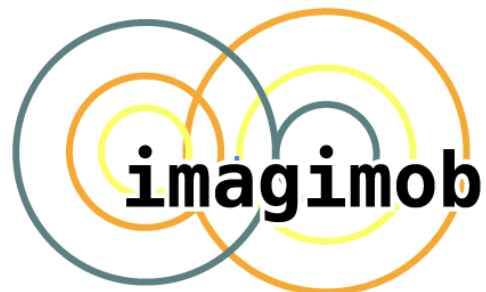
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