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Mini-NAS: A Neural Architecture Search Framework for Image Classification Applications at Edge

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- Neural Architecture Search (NAS) for benchmark image classification datasets e.g. CIFAR-10.
- What about binary classification applications for microcontrollers?
- Gradient NAS struggles, offers partial network discovery and unsuitable for constrained deployment.
- Search in existing discrete spaces e.g. with RL or evolution is expensive.

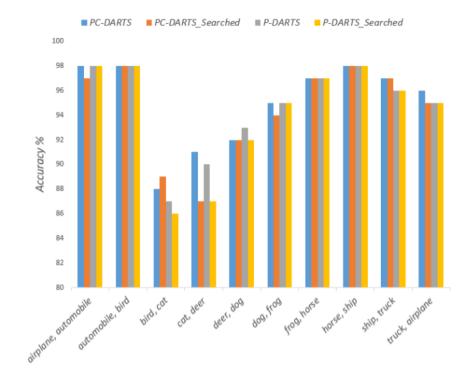


Figure 1: Gradient-based search in modular search space struggles with binary datasets. Cells searched on binary datasets are no better than cells discovered on CIFAR.



Table 1: On CIFAR-10 benchmark, Mini-NAS discovers the smallest model among methods exploring in respective global search spaces, with on par performance and search efficiency.

NAS Method			CIFAR-10	Parameters	GPU Days						
	Depth (Layers)	Width (Channels)	Operations per Layer	Convolutional Kernel	Strides	Pooling Layers	Fully Connected Layers	Skip Connections	Error (%)	(Millions)	or o buyo
NAS-RL [25]	/	~		~	~	~		~	3.65	37.4	22400
Meta-QNN [1]	~	~		~	~	~	~		6.92	11.18	100
Large-scale Evolution [14]	~	~		~	~			~	5.40	5.4	2600
EAS [2]	~	~		~	~	~	~		4.23	23.4	10
Genetic Programming CNN [18]		~		~				~	5.98	1.7	14.9
NASH-Net [7]	~	~		~				~	5.2	19.7	1
NASBOT [10]	~	~		~	~	~	~	~	8.69	N/A	1.7
Mini-NAS (Ours)	~	~	~	~					5.27	1.44	2.4

- A minimal search space with multi-level adaptability to different tasks.
- A computationally affordable search algorithm.
- Use just sufficient parameters for a given dataset.
- Competitive results on CIFAR-10 dataset.



Table 2: Mini-NAS shows negligible performance drops with significant parameter efficiency as compared to MobileNetV2.

Dataset	airplane, auto	auto, bird	bird, cat	cat, deer	deer, dog	dog, frog	frog, horse	horse, ship	ship, truck	truck, airplane	airplane, auto, bird	bird, cat, deer	deer, dog, frog	frog, horse, ship	ship, truck, airplane	airplane, auto, bird, cat
Accuracy Gain	+0.15	-0.45	-0.25	-0.8	0	0	-0.7	-0.45	-0.25	-0.2	-0.27	-1.23	-0.34	-0.06	+0.43	+0.05
Parameter Efficiency	3.1x	17.6x	8.1x	14.9x	4.4x	12.5x	103.9x	20.1x	16.2x	52x	1.8x	12.5x	12.8x	9.2x	10.6x	0.6x
Dataset	cat, deer, dog, frog	frog, horse, ship, truck	airplane, auto, bird, cat, deer	dog, frog, horse, ship, truck	CIFAR-10 All	volleyball, basketball	espresso, icecream	soda bottle, beer bottle	bucket, barrell	seashore, lakeside	egyptian cat, persian cat	limo, sports	bullfrog, tailedfrog	imagenet dogs	imagenet vehicles	
Accuracy Gain	-0.57	-0.68	-1.14	+0.05	+0.29	-1	-2	+2	+1	+1	+2	-2	+3	-3	-3.07	
Parameter Efficiency	5.9x	2.8x	2.1x	3.9x	1.6x	11.9x	8.9x	15.1x	44.4x	5.9x	5.5x	11.9x	10.1x	4.9x	8.7x	

- Experiments on many smaller datasets.
- Complete network discovery.
- Negligible accuracy drop, fewer parameters → low memory footprint.
- Pruning and quantization further broaden deployment options.
- Future research directions: MCU latency aware search, training hyper-parameter search, and real-world use cases.



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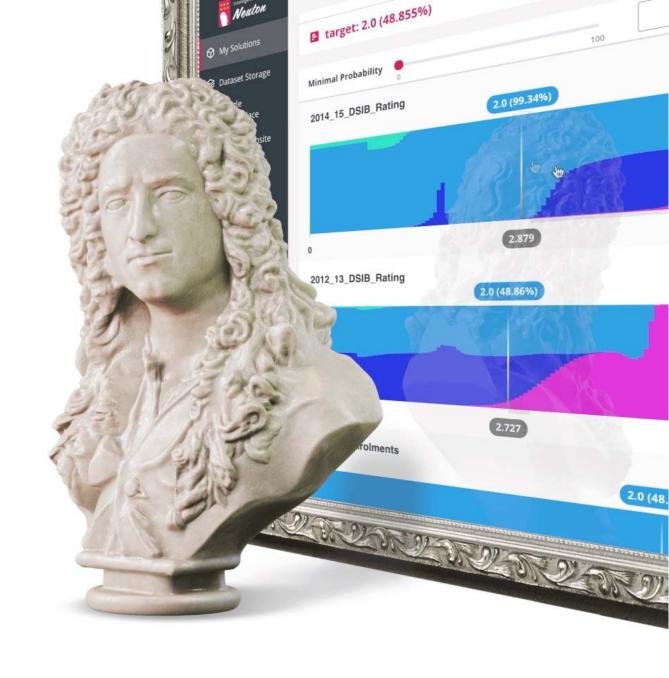
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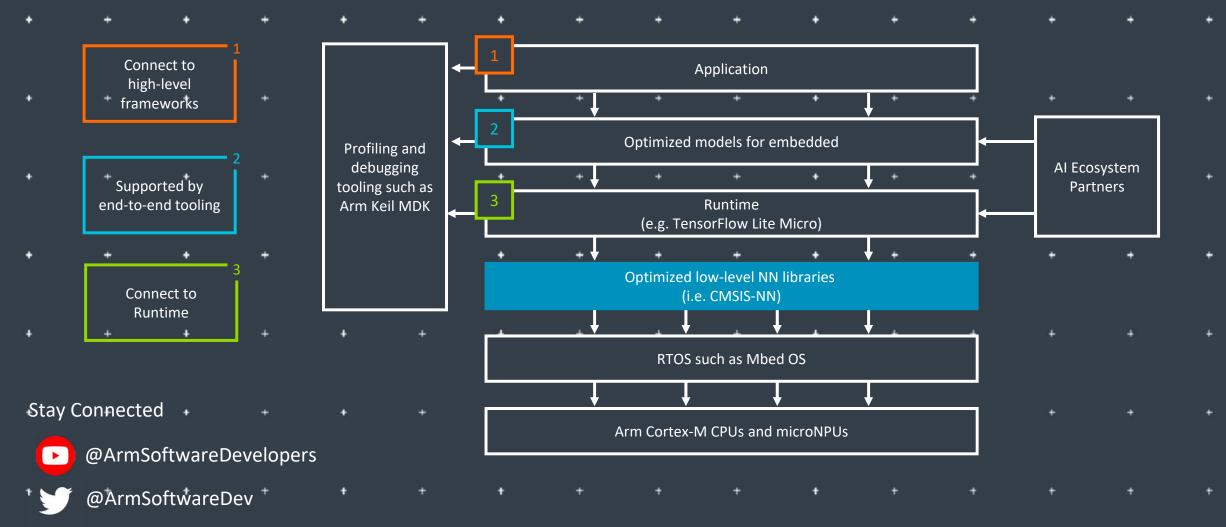
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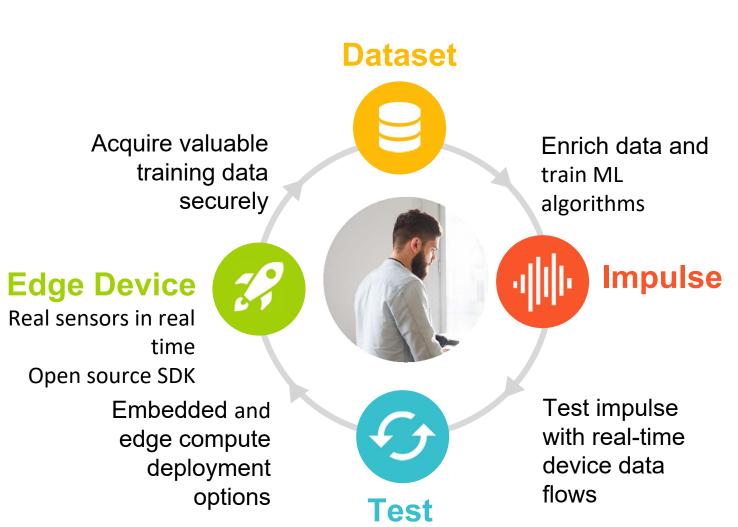


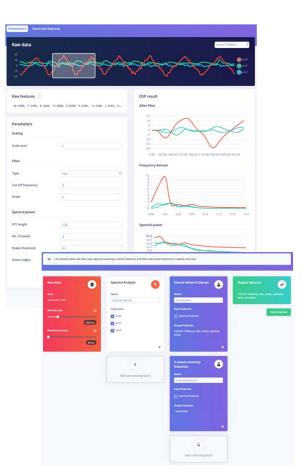
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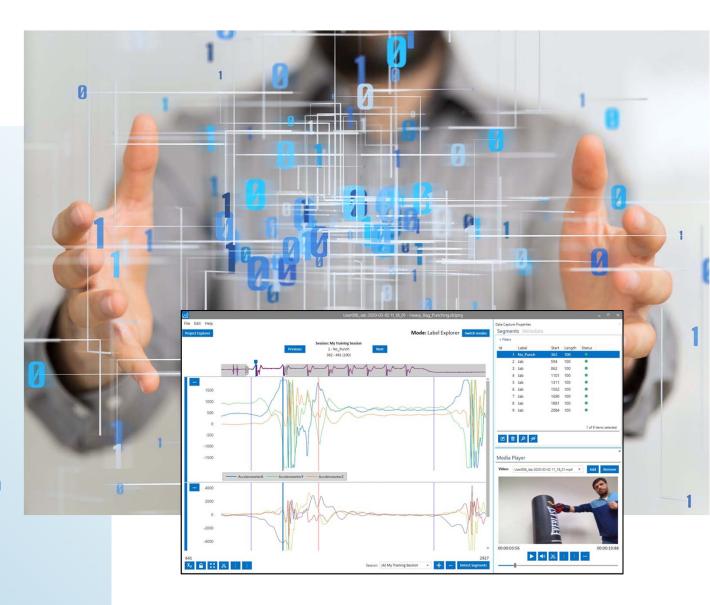


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