

tinyML[®] EMEA

Enabling Ultra-low Power Machine Learning at the Edge

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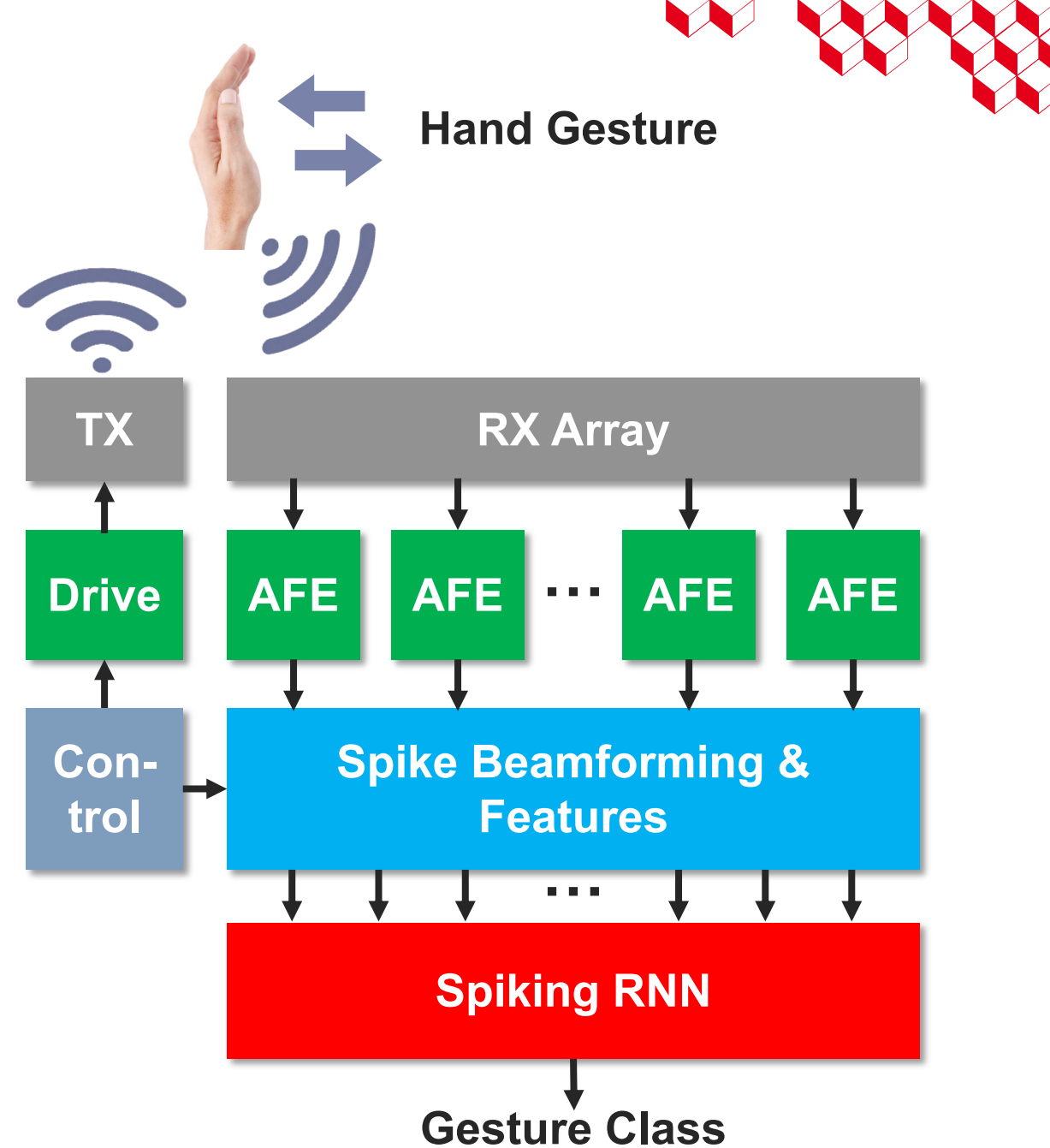
Spike-based Beamforming using pMUT Arrays for Ultra-Low Power Gesture Recognition

Emmanuel Hardy



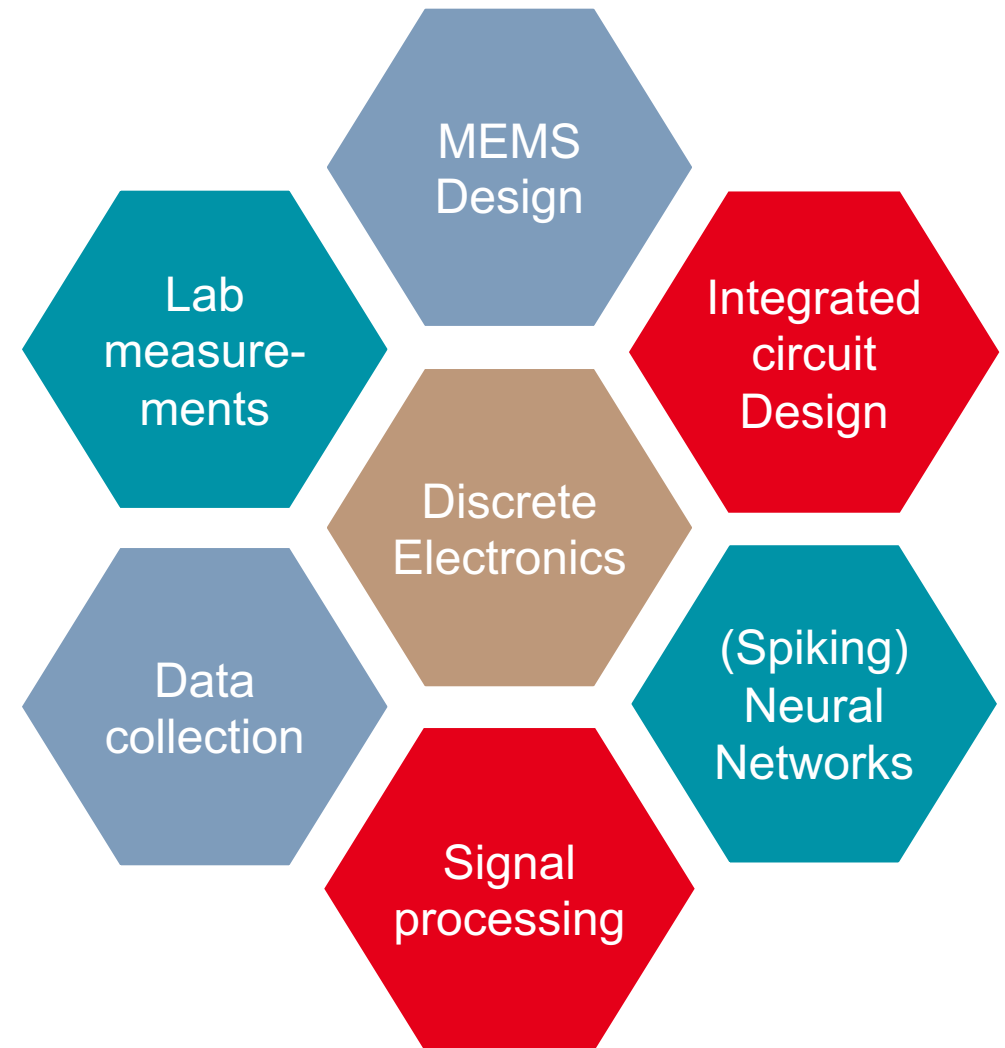
System Overview

- > End-to-end Ultrasonic Gesture Recognition with pMUTs
- > Competing technologies: IR, electric field, radar, camera.
- > Key advantages:
 - Insensitivity to light/shadow
 - Low cost
 - Low power



Key Points

- › **End-to-end Power Efficient Edge AI device**
 - Efficient sensors
 - Analog-to-information conversion
 - Low power inference
- › **Needs a widely cross-functional team**



The team

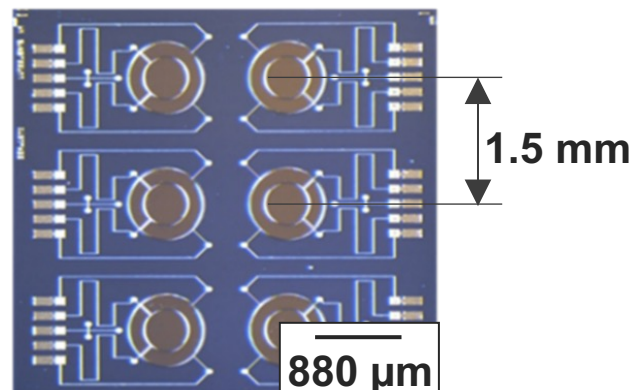
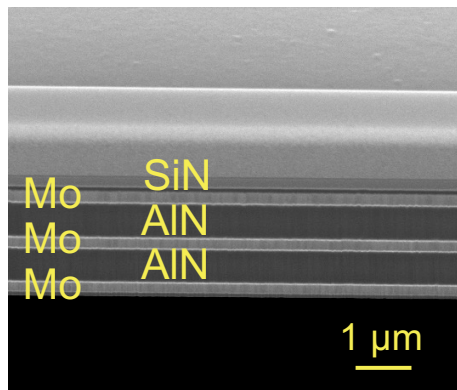
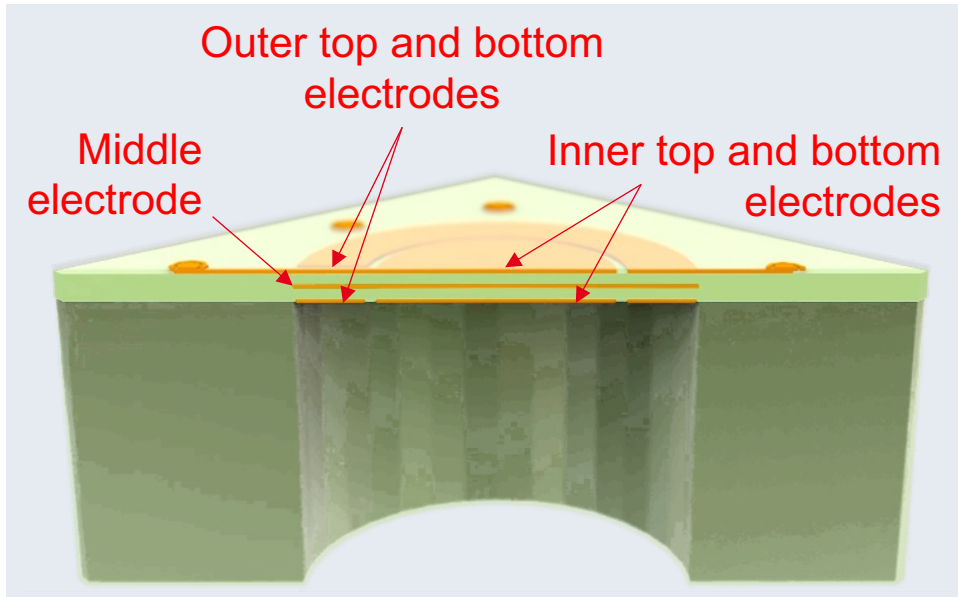
- › Bruno Fain
- › Thomas Mesquida
- › François Blard
- › François Gardien
- › François Rummens
- › Jean-Claude Bastien
- › Jean-Rémi Chatroux
- › Sébastien Martin
- › Venceslass Rat
- › Elisa Vianello

E. Hardy *et al.*, “Spike-based Beamforming using pMUT Arrays for Ultra-Low Power Gesture Recognition,” in *2022 IEDM*, Dec. 2022,
doi: [10.1109/IEDM45625.2022.10019395](https://doi.org/10.1109/IEDM45625.2022.10019395).



1 ■ **Sensor Array**

PMUTs Transducers

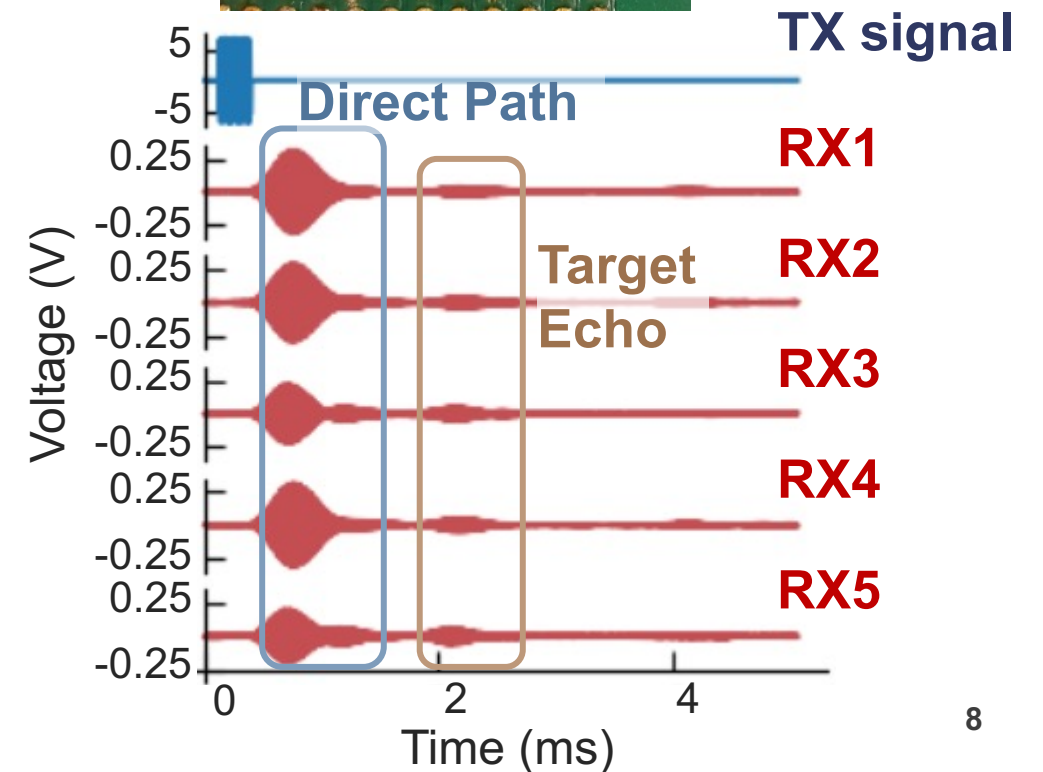
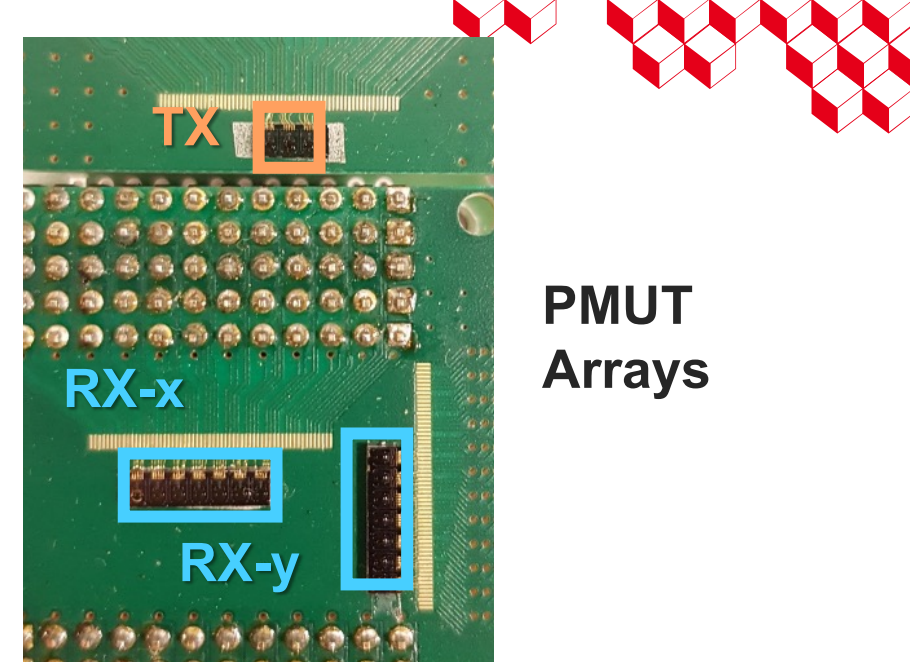


PMUT: Piezoelectric Micromachined Ultrasonic Transducer

- › Aluminum nitride piezo material
- › Bimorph structure for higher sensitivity and TX power
- › Resonance ~ 100kHz (tunable)
- › 8" MEMS production line in CEA-Leti

Acoustic setup

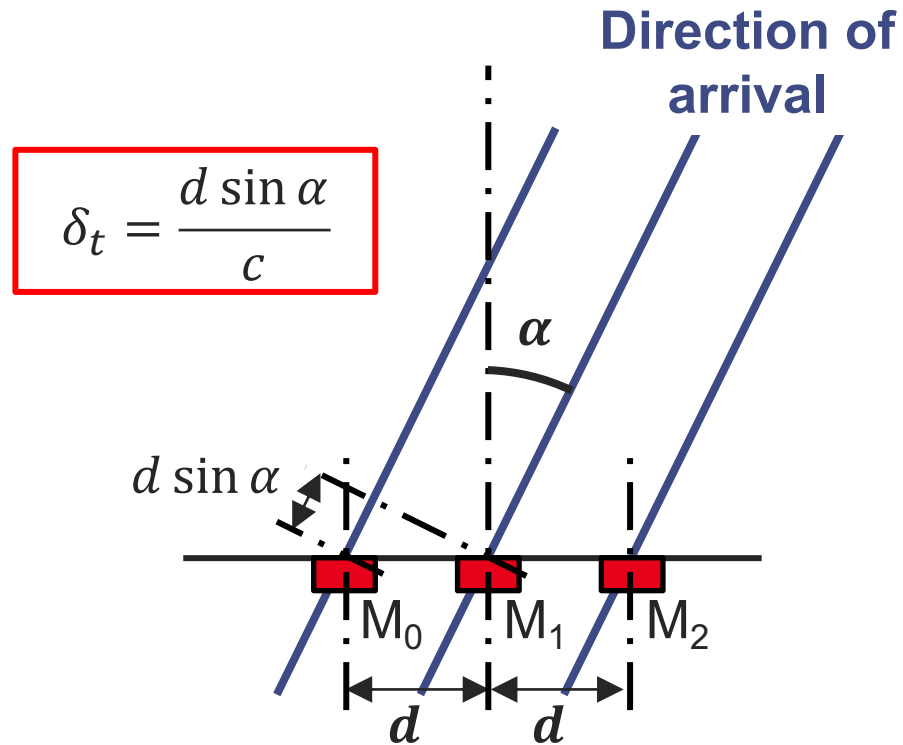
- > TX: 1 PMUT
- > RX: 2 orthogonal arrays of 5 PMUTs
- ✓ 3D sensing
- > Range: 10 -> 60 cm



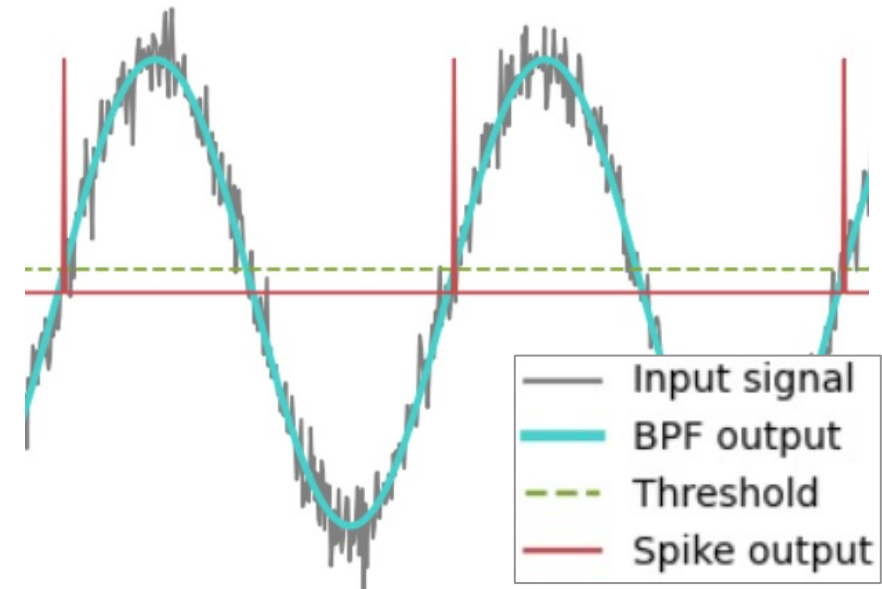


2 ■ **Spike-based signal processing**

Spike-based Beamforming

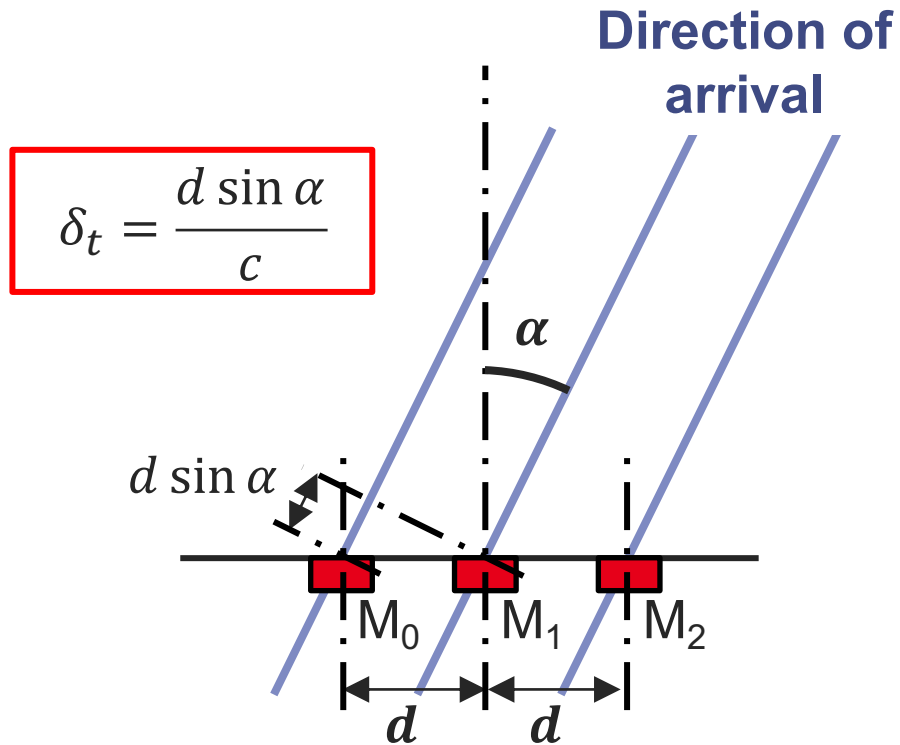


**Time Difference of Arrival
between M_0 and M_1**

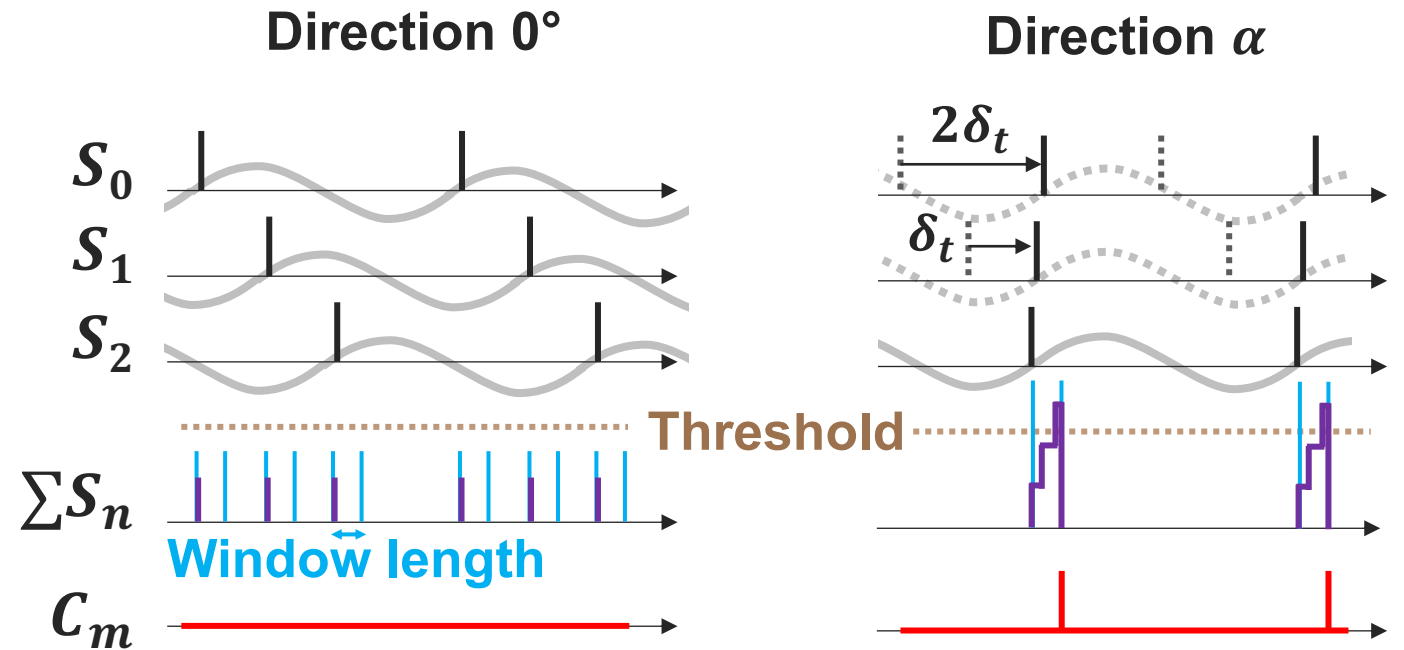


Conversion to spikes

Spike-based Beamforming



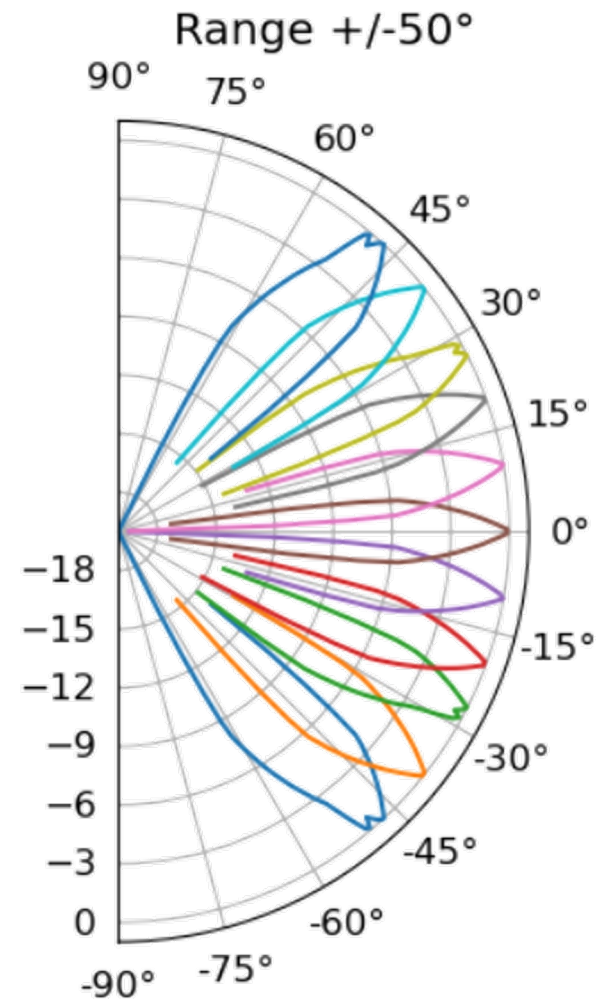
**Time Difference of Arrival
between M_0 and M_1**



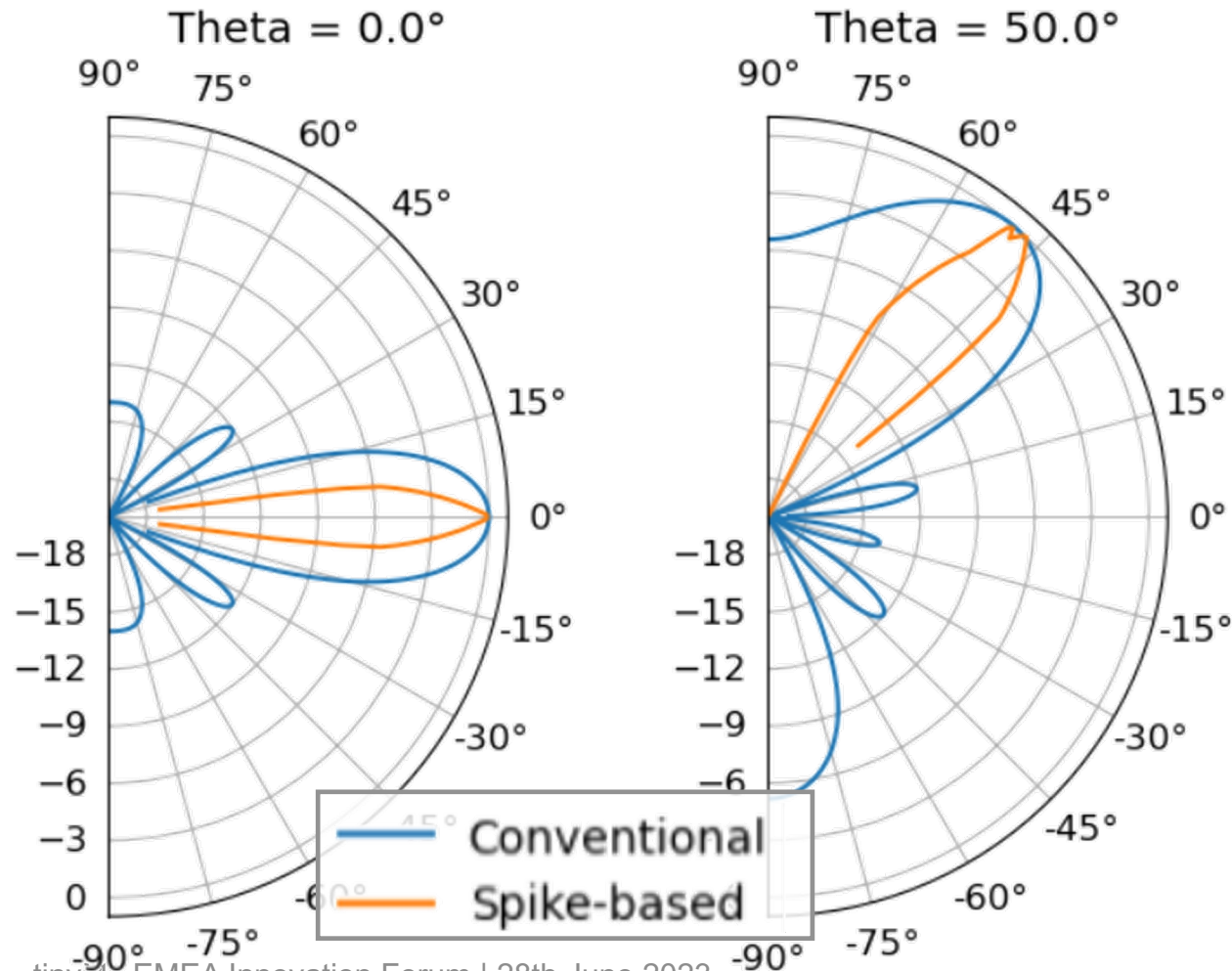
Spike Coherence Detection

Spike-based Beamforming

- › 11 directions
- › $\pm 50^\circ$ range with 10° steps
- › Optimal threshold and window size

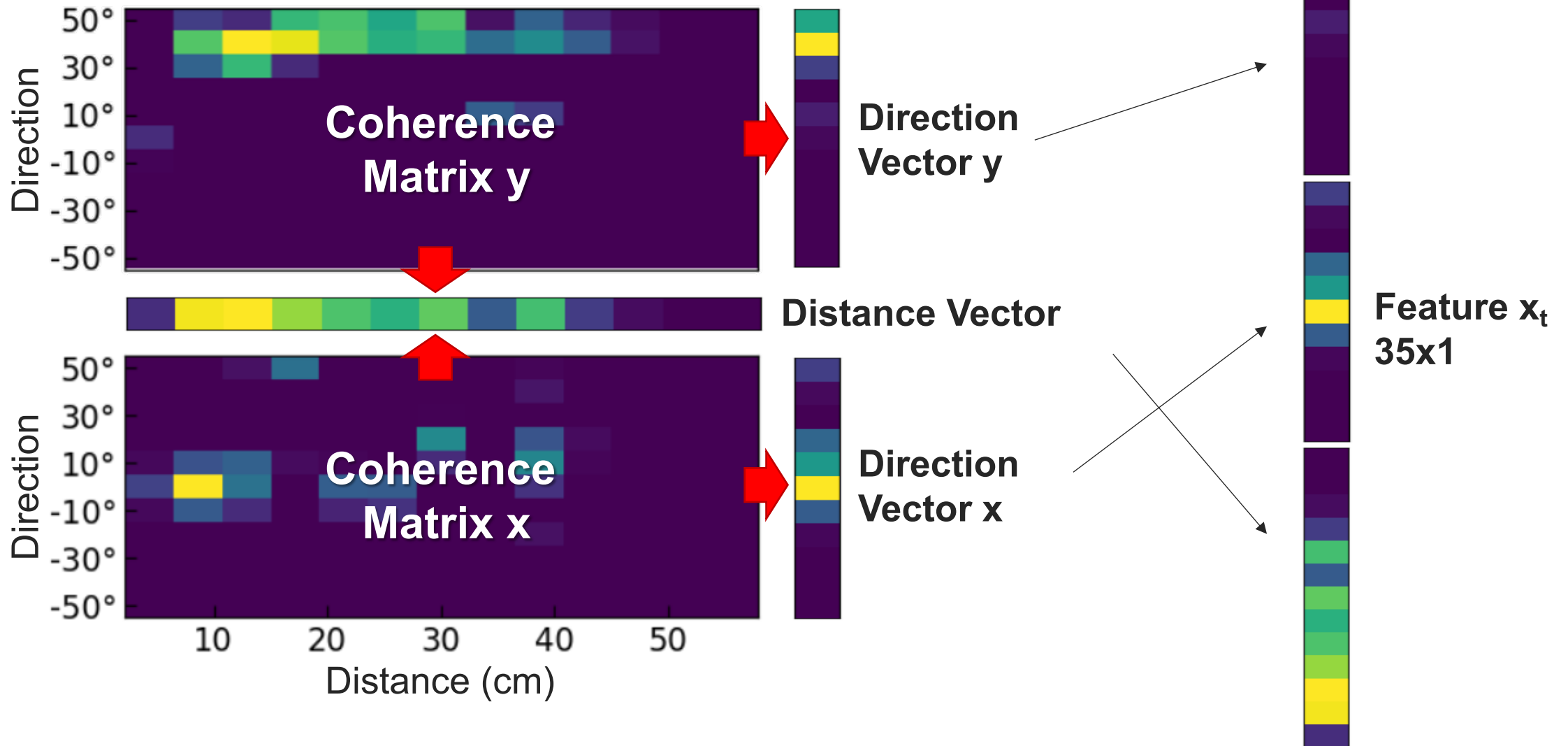


Spike-based Beamforming

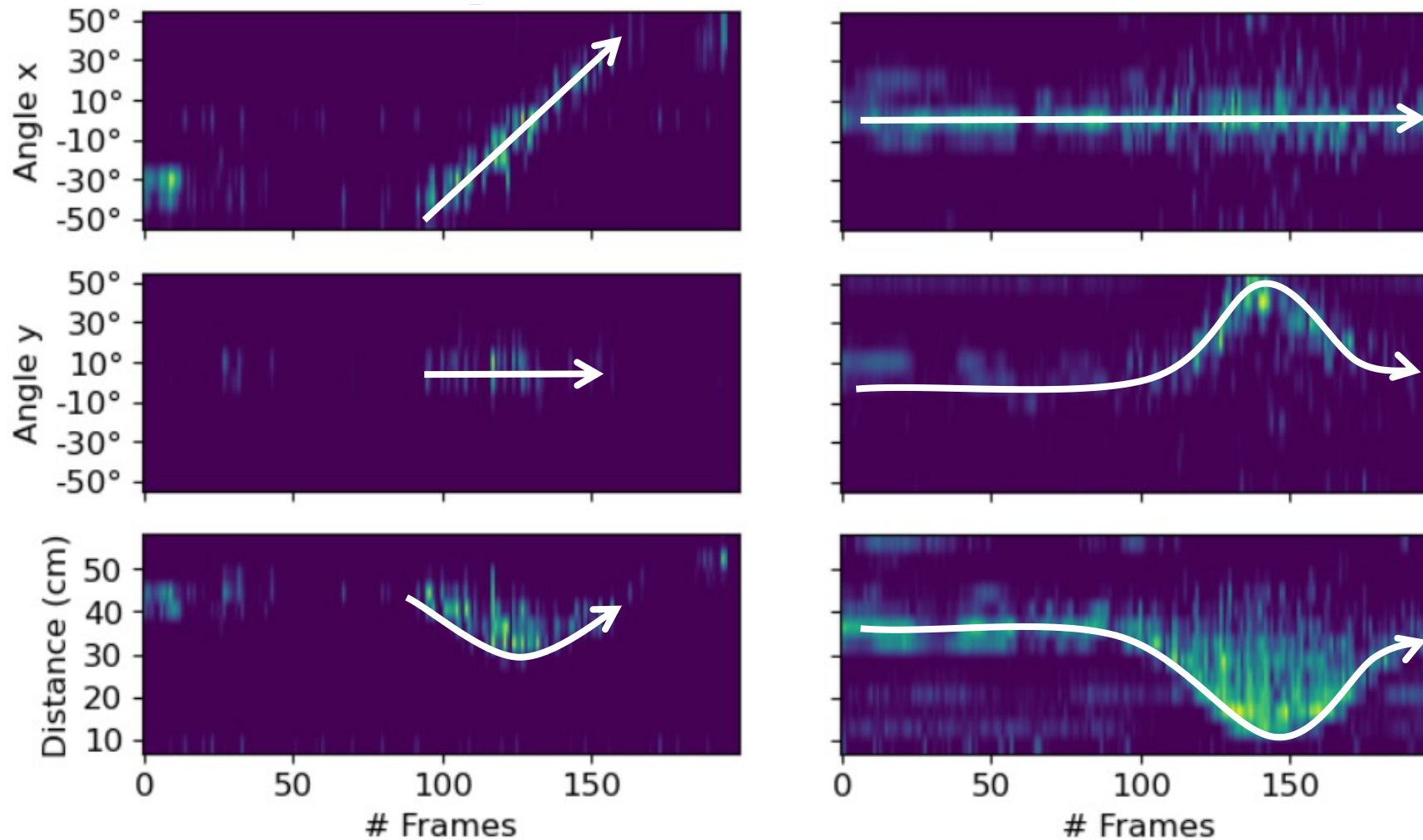


- > wrt. **Conventional Beamforming**
 - ~3 times better angular selectivity at 0°
 - No side lobes
 - Increased range
- > **BUT not proportional to signal amplitude.**

Feature Vector



Example of Gestures





3 ■ **Classification & Results**

Gesture Classifier

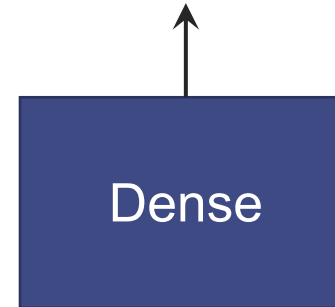
> Recurrent Neural Network

- Trainable Temporal Dependency (no fixed window)
- Computational Efficiency

> Two classifiers:

1. GRU Baseline
2. Spiking RNN Hardware Target

Output
Probabilities (6)

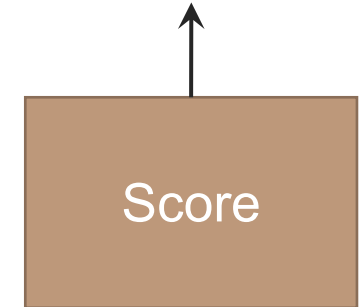


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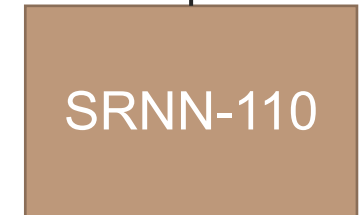


Input features
(35)

Output
Scores (6)

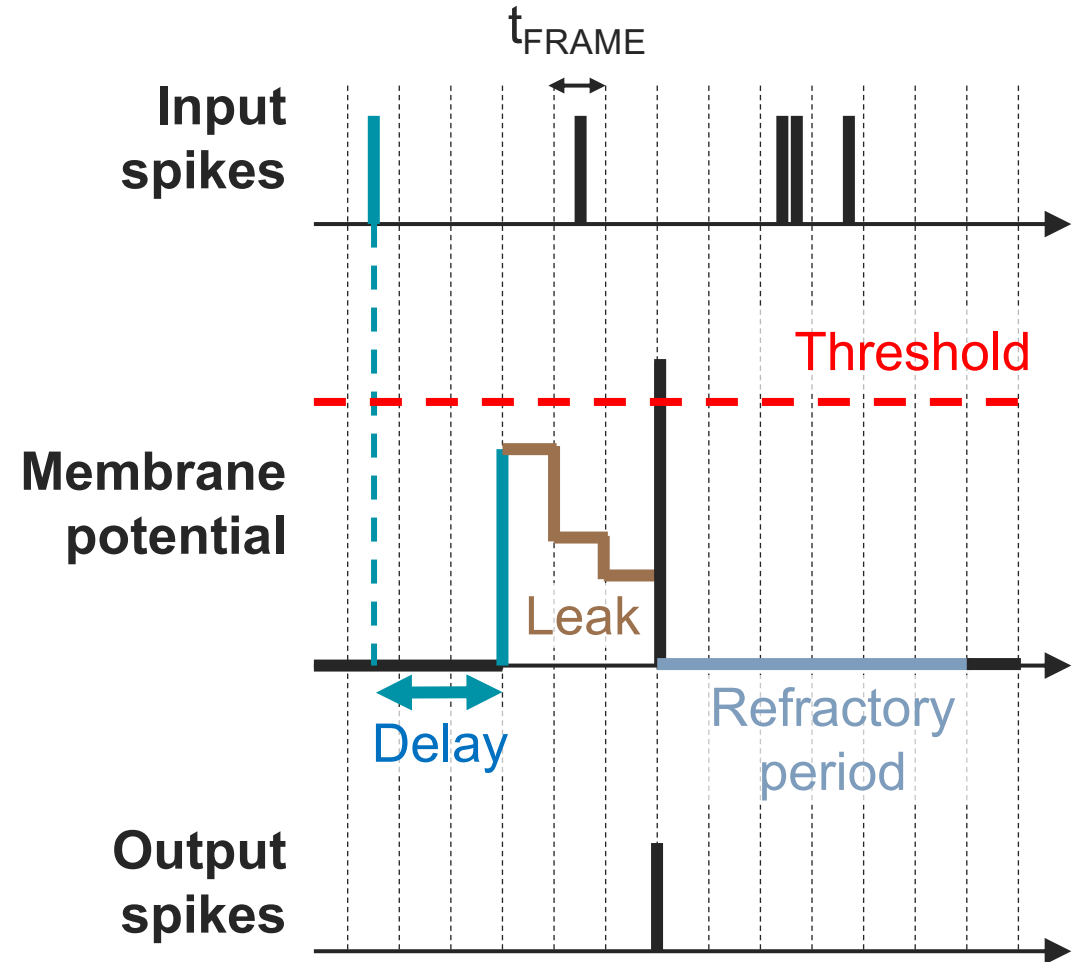
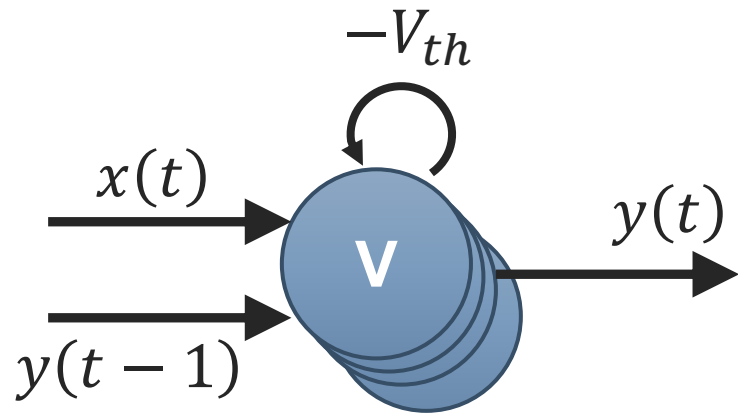


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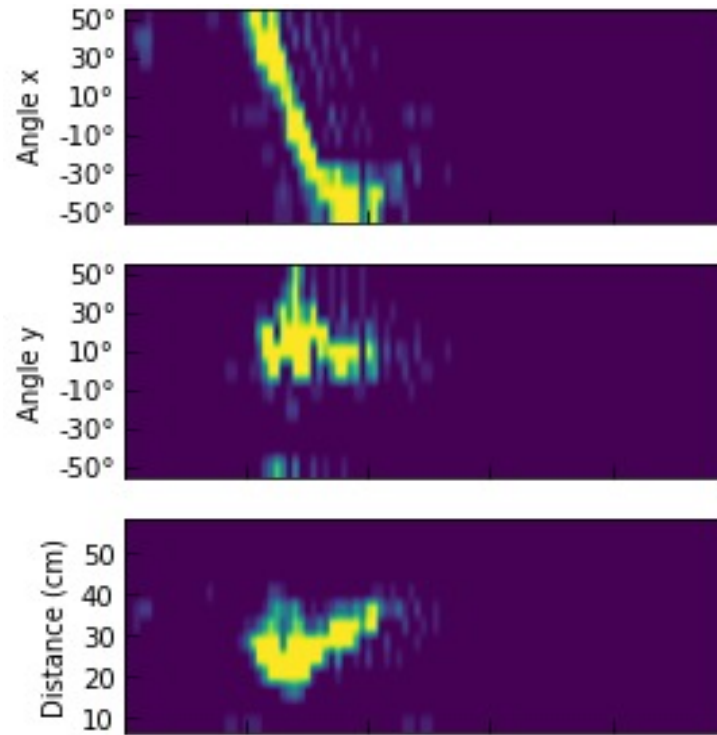


Input features
(35)

Spiking Recurrent Unit

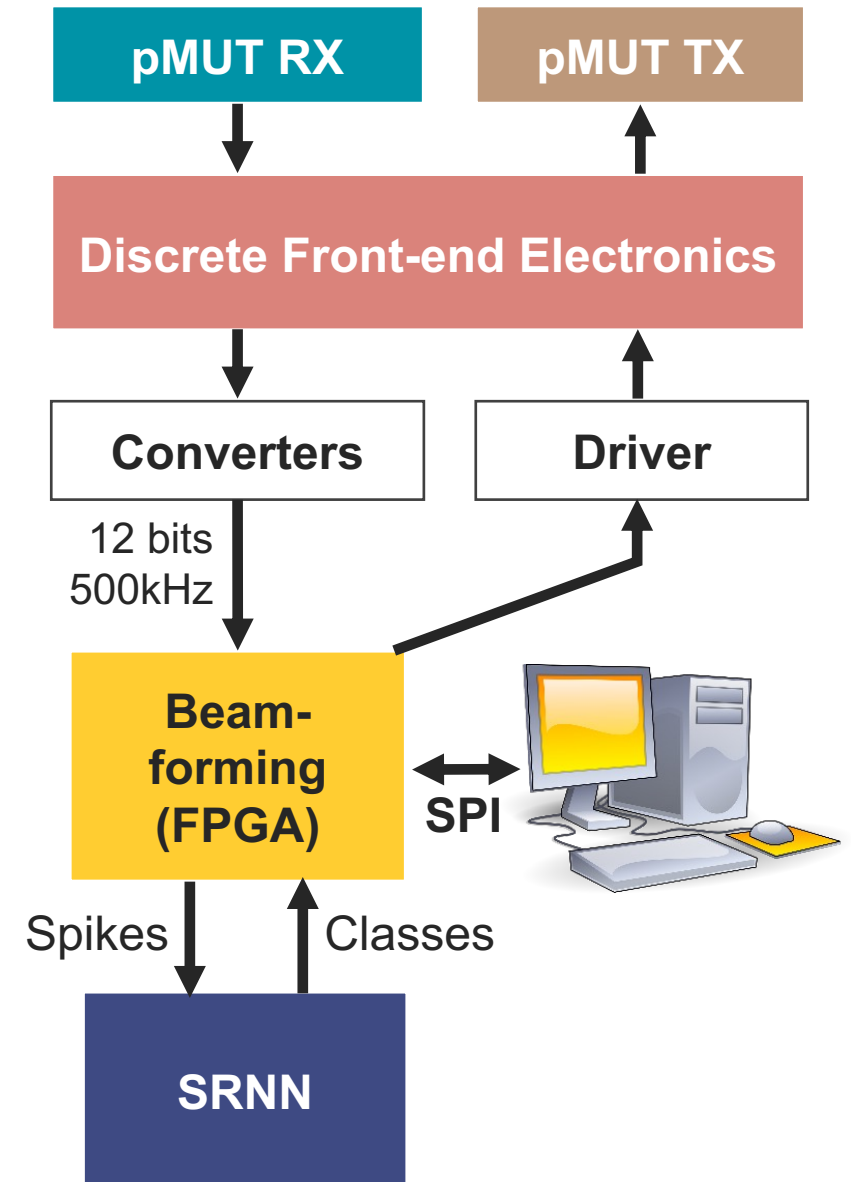
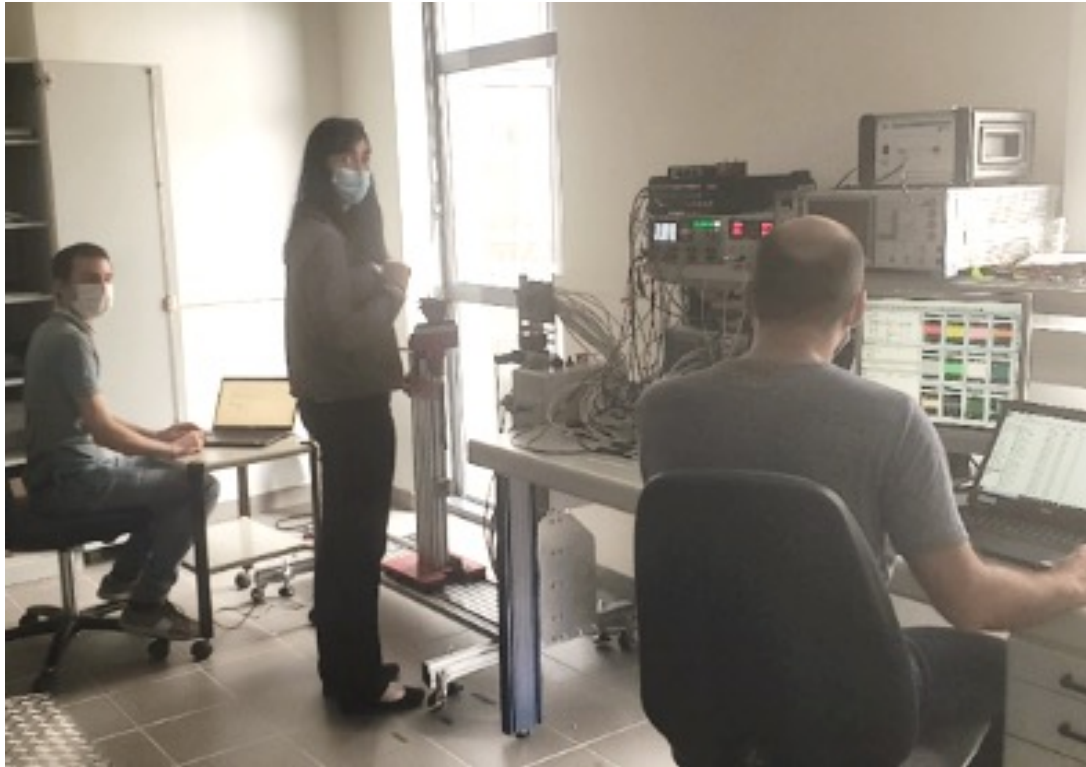


Right-Left example

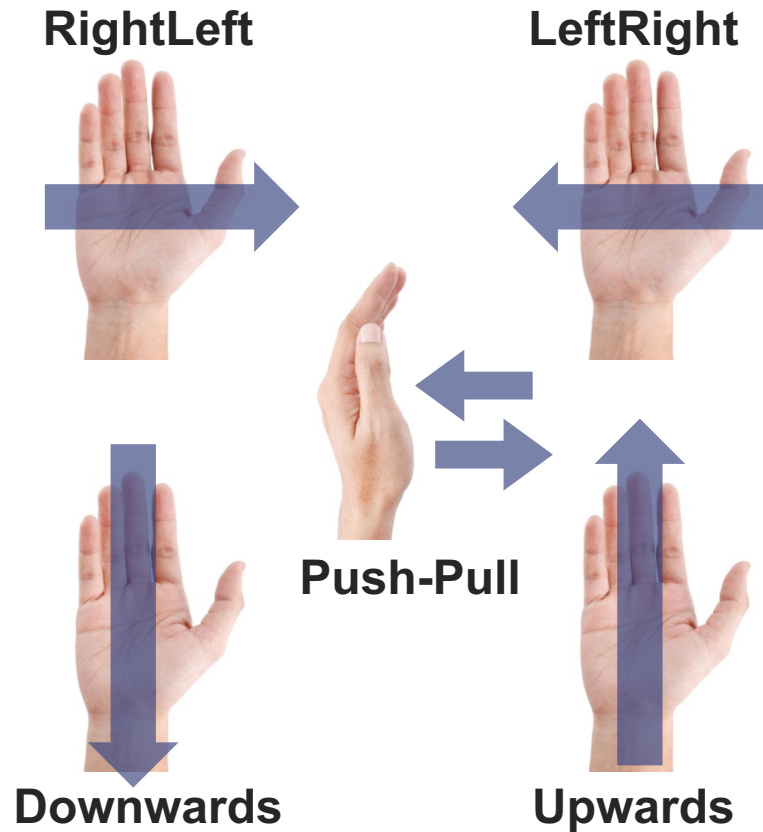


**4 bits Feature
Quantization**

Experimental Setup

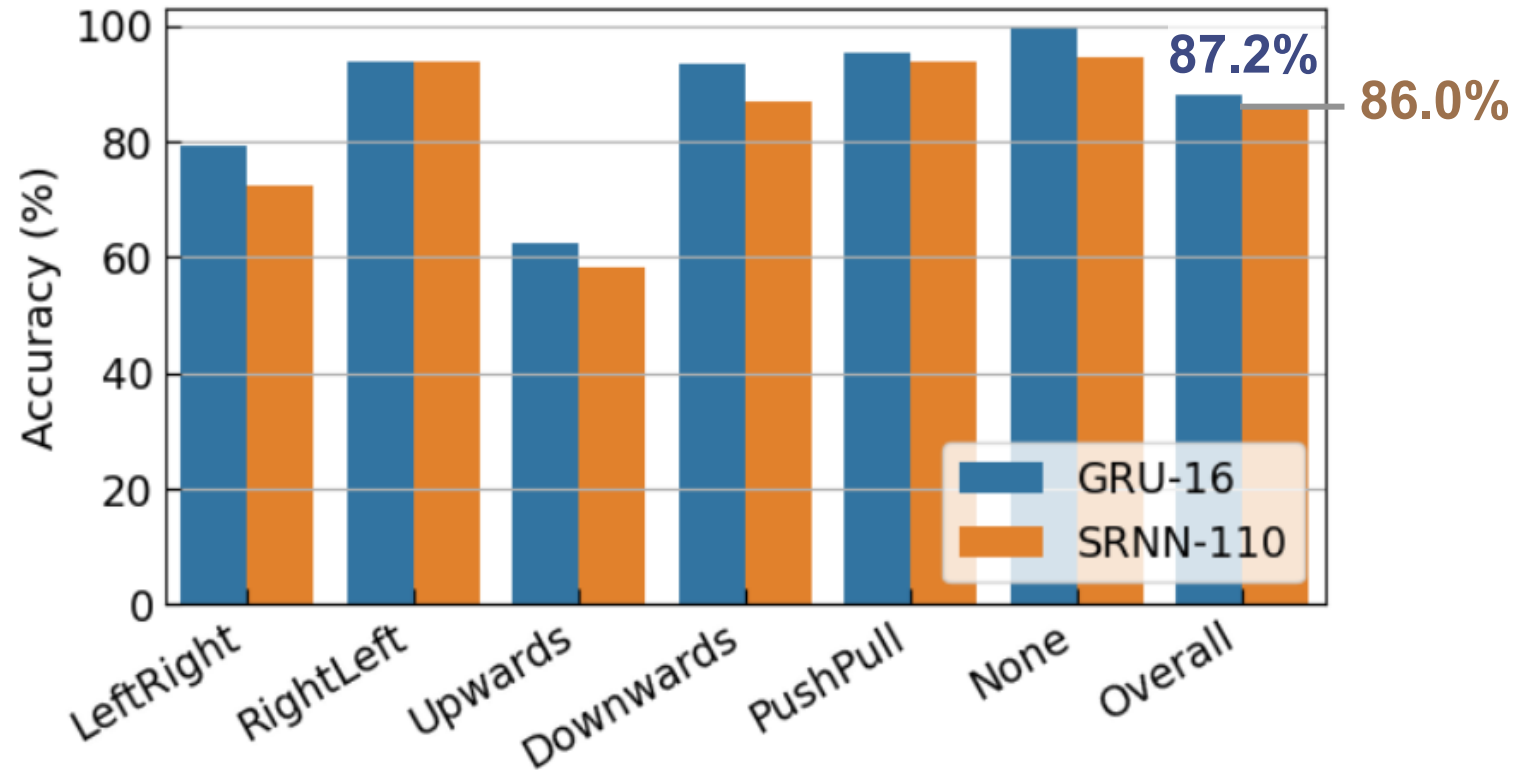


Gesture Dataset



- > 5 gestures + None class
- > 499 examples, 12 participants
 - Training/test (9/3 split)
- > 10 to 50 cm distance
- > Data augmentation for training
 - System symmetry

Classification Results



Small accuracy drop with SRNN

Classification Results

Predicted

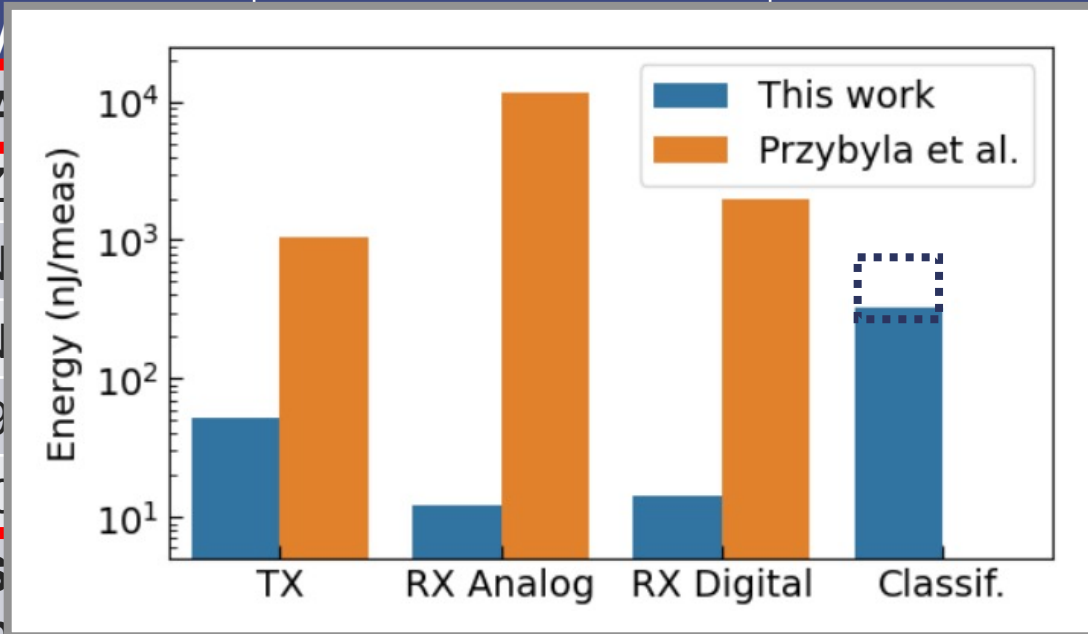
True

	LeftRight	RightLeft	Upwards	Downwards	PushPull	None
LeftRight	72.4%	0.0%	0.0%	3.4%	10.3%	13.8%
RightLeft	0.0%	93.8%	0.0%	0.0%	0.0%	6.2%
Upwards	0.0%	4.2%	58.3%	0.0%	29.2%	8.3%
Downwards	0.0%	0.0%	0.0%	86.7%	6.7%	6.7%
PushPull	1.6%	0.0%	0.0%	0.0%	93.7%	4.8%
None	0.0%	0.0%	0.0%	0.0%	5.4%	94.6%

Gesture ambiguity, small dataset

State-of-the-Art

	This work	Przybyla et al.	TS
Type of transducers	TX-RX: AIN pMUT	TX-RX: A	
# RX - Pattern	10 - 2 Lines X/Y	7 - Z	
Classif. type	SRNN	N	est
Accuracy	86.0% (5 gest.)	N	st.)
Meas. period	40 ms	5.9	
Max. range	60 cm	100	
Hardware integration	COTS	AS	
Est. sensing energy (ASIC)	78.1 nJ/meas.	15.6 μ J/meas.	Not measured
Est. inference energy (ASIC)	330/760 nJ/meas. (None/Gesture)	N/A	Not measured





Wrapping Up...

Applications and Perspectives

› Gesture Recognition

- Wearables, automotive, VR headsets.

› Robotics

- Obstacle detection
- Beamforming at emission

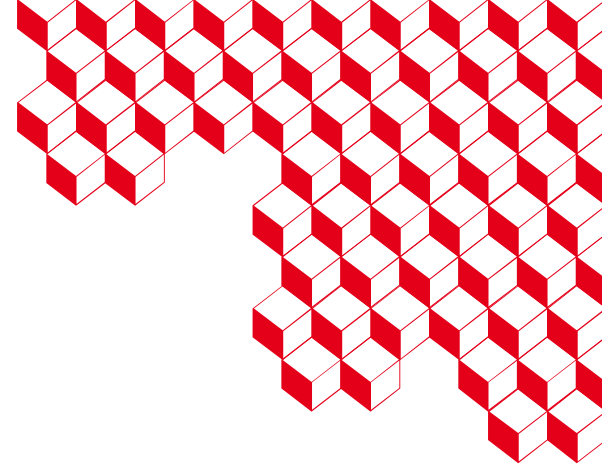
› What's Next

- Apply this approach to new sensors from CEA Leti
- Build new exciting prototypes and ASICs

Takeaway Points

1. Small form factor pMUT array
2. Beamforming & Signal Processing in the Spike domain
3. Low Power Gesture Classification

Analog-to-Information strategy to yield more efficient Sensors + Edge AI systems.



Thank you!

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